

Serie 2

Context: Galerkin approximation.

Theoretical Exercises: 1.–5.

Practical Exercise: 6.

Let V_N and W_N be two finite dimensional spaces with $\dim(V_N) = N$ and $\dim(W_N) = P$. Let $A_N : V_N \rightarrow (W_N)'$ be a linear operator. Let f_N be an element of $(W_N)'$

$$\text{Find } u_N \in V_N, \quad \text{such that } A_N u_N = f_N. \quad (1)$$

We introduce a basis $\mathfrak{B}_V = \{p_N^1, \dots, p_N^N\}$ (resp. $\mathfrak{B}_W = \{q_N^1, \dots, q_N^P\}$) of V_N (resp. W_N). Finally, we consider the problem:

$$\text{Find } \mathbf{u}_N \in \mathbb{C}^N \quad \mathbf{A}_N \mathbf{u}_N = \mathbf{f}_N, \quad (2)$$

with

$$\left\{ \begin{array}{l} \mathbf{A}_N = \left(\left\langle A_N p_N^i; q_N^j \right\rangle_{W_N} \right)_{j,i=1}^{P,N} \in \mathbb{C}^{P \times N}, \\ \mathbf{f}_N = \left(\left\langle f; q_N^j \right\rangle_{W_N} \right)_{j=1}^P \in \mathbb{C}^P, \\ u_N = \sum_{i=1}^N \mathbf{u}_N^i p_N^i. \end{array} \right. \quad (3)$$

1. (a) Show that problem (1) is equivalent to problem (2).

(b) Prove that:

$$\text{the problem (1) has generically } (\forall f) \text{ one solution} \quad \implies \quad N = P. \quad (4)$$

Hint: Use that $\dim(\text{Rg}(A_N)) + \dim(\text{Ker}(A_N)) = N$.

2. We set $N = P$, $V_N = W_N$ and $\mathfrak{B}_V = \mathfrak{B}_W$.

Compute the new Galerkin matrix $\underline{\mathbf{A}}_N$ and the right hand side vector $\underline{\mathbf{f}}_N$ for problem (1) after a permutation of the basis vectors of \mathfrak{B}_V .

Hint: Introduce a permutation matrix \mathbf{P} .

Bitte wenden!

3. We set $V_N = W_N$ and $\mathfrak{B}_V = \mathfrak{B}_W$. We denote by \mathfrak{B}_V^2 the basis obtained by scaling the basis vectors of \mathfrak{B}_V :

$$\mathfrak{B}_V^2 = (\alpha_N^i p_N^i)_{i=1}^N \quad \text{with } \forall i = 1, \dots, N \quad \alpha_N^i \in \mathbb{R}^*. \quad (5)$$

Express \mathbf{A}_N^2 and \mathbf{f}_N^2 with respect to $\mathbf{A}_N, \mathbf{f}_N, \alpha_N^i$, where \mathbf{A}_N^2 and \mathbf{f}_N^2 are the Galerkin matrix associated to problem (1) and to the basis \mathfrak{B}_V^2

4. The operator equation (1) is set in finite dimensional spaces. Hence, after choosing bases for V_N and $(W_N)'$ it can be converted into a linear system of equations. Which bases have to be chosen, such that we exactly end up with (2)?

5. We set $N = P$, and we suppose that A_N is bijective:

For a fixed basis $\mathfrak{B}_W = (q_N^i)_{i=1}^N$ of W_N , define a basis $\mathfrak{B}_V = (p_N^i)_{i=1}^N$ of V_N such that:

$$u_N = \sum_{i=1}^N \langle f_N; q_N^i \rangle p_N^i \quad (6)$$

where u_N is the solution of problem (1). What is the Galerkin matrix \mathbf{A}_N associated to \mathfrak{B}_V and \mathfrak{B}_W ?

6. Consider the bilinear form:

$$\begin{cases} \mathbf{a} : L^2([0; 1]) \times L^2([0; 1]) & \rightarrow \mathbf{R} \\ (u, v) & \mapsto \int_0^1 u(x) v(x). \end{cases} \quad (7)$$

(a) Does this bilinear form satisfy the inf-sup condition in $L^2([0; 1])$?

(b) We set:

$$V_N = \text{span}(\mathfrak{B}_V) \subset L^2([0; 1]) \quad \text{and} \quad W_N = \text{span}(\mathfrak{B}_W) \subset W \subset L^2([0; 1]), \quad (8)$$

with:

$$\begin{cases} \mathfrak{B}_V = \{p_N^k : [0; 1] \rightarrow \mathbf{R}, x \mapsto x^k \mid k = 0, \dots, N-1\}, \\ \mathfrak{B}_W = \{q_N^k : [0; 1] \rightarrow \mathbf{R}, x \mapsto \mathbb{I}_{[\frac{k}{n}, \frac{k+1}{n}]}(x) \mid k = 0, \dots, N-1\}, \end{cases} \quad (9)$$

where $\mathbb{I}_I(x) = 1$ if $x \in I$ and 0 else.

Compute the Galerkin matrix \mathbf{A}_N .

(c) Write a MATLAB code which computes the inf-sup constant γ_N for some N 's.

Siehe nächstes Blatt!

Tutorial: Thursday 10–11 HG E5, **Starting time:** Thursday, 3.10

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Testat requirement: 50% of the theoretical exercises and 50% practical exercises (MAT-
LAB) should be solved.

Appendix: Singular Value Decomposition (SVD):

Let \mathbf{A} be an element of $\mathbb{C}^{N \times N}$. We will show that there exist $\mathbf{U} \in \mathbb{C}^{N \times N}$ unitary and $\mathbf{V} \in \mathbb{C}^{N \times N}$ unitary and $\mathbf{D} \in \mathbb{C}^{N \times N}$ diagonal such that:

$$\mathbf{A} = \mathbf{U} \mathbf{D} \mathbf{V}^H. \quad (10)$$

First, we consider $\mathbf{A} \mathbf{A}^H \in \mathbb{C}^{N \times N}$. This is a symmetric matrix. Therefore, there exist $\mathbf{U} \in \mathbb{C}^{N \times N}$ unitary and $\mathbf{D}_2 \in \mathbb{C}^{N \times N}$ diagonal satisfying:

$$\mathbf{A} \mathbf{A}^H = \mathbf{U} \mathbf{D}_2 \mathbf{U}^H \quad (11)$$

In other words, there exist N vectors \mathbf{u}_i and N scalars λ_i such that:

$$\mathbf{A} \mathbf{A}^H \mathbf{u}_i = \lambda_i \mathbf{u}_i, \quad \text{for all } i = 1, \dots, N. \quad (12)$$

where the \mathbf{u}_i 's are the columns of the matrix \mathbf{U} and λ_i are the coefficients of the diagonal matrix \mathbf{D}_2 . The \mathbf{u}_i satisfies the orthogonal property:

$$\mathbf{U}^H \mathbf{U} = \mathbf{I} \iff \mathbf{u}_i^H \mathbf{u}_j = 1 \text{ if } i = j \quad \text{and} \quad 0 \text{ else.} \quad (13)$$

We define the \mathbf{v}_i in the following way :

$$i \in I = \{i \in \mathbb{N} \text{ with } 1 \leq i \leq N \text{ and } \mathbf{A}^H \mathbf{u}_i \neq 0\}, \quad \mathbf{v}_i =: \frac{\mathbf{A}^H \mathbf{u}_i}{\|\mathbf{A}^H \mathbf{u}_i\|}. \quad (14)$$

Remarking that $\forall i \in I$:

$$\begin{cases} \|\mathbf{A}^H \mathbf{u}_i\|^2 = (\mathbf{A}^H \mathbf{u}_i; \mathbf{A}^H \mathbf{u}_i) = (\mathbf{A} \mathbf{A}^H \mathbf{u}_i; \mathbf{u}_i) = \lambda_i, \\ (\mathbf{A}^H \mathbf{u}_i; \mathbf{A}^H \mathbf{u}_j) = (\mathbf{A}^H \mathbf{u}_i; \mathbf{A}^H \mathbf{u}_j) = (\mathbf{A} \mathbf{A}^H \mathbf{u}_i; \mathbf{u}_j) = \lambda_i (\mathbf{u}_i; \mathbf{u}_j), \end{cases} \quad (15)$$

leads to for all i and j in I :

$$\mathbf{v}_i^H \mathbf{v}_j = 1 \text{ if } i = j \quad \text{and} \quad 0 \text{ else.} \quad (16)$$

Bitte wenden!

By the Gram-Schmidt procedure, we complete the system of vectors $(\mathbf{v}_i)_{i \in I}$ so that the completed version $(\mathbf{v}_i)_{i=1}^N$ keep the orthogonality property (16). By construction, one has:

$$\sqrt{\lambda_i} \mathbf{v}_i = \mathbf{A}^H \mathbf{u}_i, \quad \forall i = 1, \dots, N. \quad (17)$$

Now, we denote by $\mathbf{V} \in \mathbb{C}^{N \times N}$ and $\mathbf{D} \in \mathbb{C}^{N \times N}$ the matrices given by:

$$\mathbf{V} = (\mathbf{v}_1 | \mathbf{v}_2 | \dots | \mathbf{v}_N) \quad \text{and} \quad \mathbf{D} = \sqrt{\mathbf{D}_2}. \quad (18)$$

The matrix $\mathbf{V} \in \mathbb{C}^{N \times N}$ is unitary and the matrix $\mathbf{D} \in \mathbb{C}^{N \times N}$ is diagonal with $\mathbf{D}_{i,i} = \sqrt{\lambda_i}$. Finally, equations (16) and (17) lead to:

$$\mathbf{D} = \mathbf{V}^H \mathbf{A}^H \mathbf{U} \implies \mathbf{V} \mathbf{D} \mathbf{U}^H = \mathbf{A}^H \implies \mathbf{A} = \mathbf{U} \mathbf{D} \mathbf{V}^H. \quad (19)$$

We say that the $\sqrt{\lambda_i}, i = 1, \dots, N$, are the singular values of the matrix \mathbf{A} .

Matlab command:

`[U, S, V] = svd(A)` produces a diagonal matrix S , of the same dimension as X and with nonnegative diagonal elements in decreasing order, and unitary matrices U and V so that $\mathbf{A} = \mathbf{U}^* \mathbf{S}^* \mathbf{V}^*$.

`S = svd(A)` returns a vector containing the singular values.

`Smin = svds(A, 1, 0)` returns the smallest singular value.