

### Exercice 1:

$$\begin{aligned}\nabla \cdot (f \vec{v}) &= \operatorname{div} (f \vec{v}) \\ &= \partial_x (f v_x) + \partial_y (f v_y) + \partial_z (f v_z) \\ &= (\partial_x f) v_x + (\partial_y f) v_y + (\partial_z f) v_z \\ &\quad + f \partial_x v_x + f \partial_y v_y + f \partial_z v_z \\ &= \vec{\nabla} f \cdot \vec{v} + f \operatorname{div} \vec{v}.\end{aligned}$$

### Exercice 2:

$$\operatorname{div} \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

$$J_{(r, \theta, z) \rightarrow (x, y, z)} = \begin{bmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$J_{(x, y, z) \rightarrow (r, \theta, z)} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ \frac{1}{r} \sin \theta & \frac{1}{r} \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial z}{\partial x} \frac{\partial}{\partial z} = \cos \theta \frac{\partial}{\partial r} - \frac{1}{r} \sin \theta \frac{\partial}{\partial \theta}$$

$$\frac{\partial}{\partial y} = \sin \theta \frac{\partial}{\partial r} + \frac{1}{r} \cos \theta \frac{\partial}{\partial \theta}$$

$$\frac{\partial}{\partial z} = \frac{\partial}{\partial z}$$

$$v_x = v_r \cos \theta - v_\theta \sin \theta$$

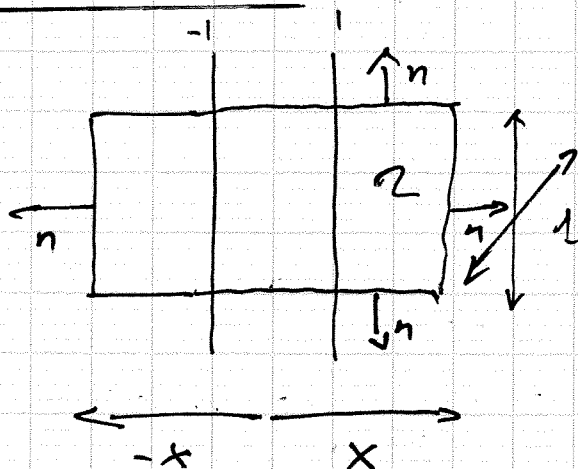
$$v_y = v_r \sin \theta + v_\theta \cos \theta$$

$$v_z = v_z$$

$$\begin{aligned} \operatorname{div} \vec{v} &= \cos^2 \theta \frac{\partial}{\partial r} v_r - \cos \theta \sin \theta \frac{\partial v_\theta}{\partial r} \\ &\quad + \sin^2 \theta \frac{\partial}{\partial r} v_r + \cos \theta \sin \theta \frac{\partial v_\theta}{\partial r} \\ &\quad - \frac{1}{r} \sin \theta \frac{\partial}{\partial \theta} (v_r \cos \theta - v_\theta \sin \theta) \\ &\quad + \frac{1}{r} \cos \theta \frac{\partial}{\partial \theta} (v_r \sin \theta + v_\theta \cos \theta) \\ &\quad + \frac{\partial}{\partial z} v_z \\ &= \frac{\partial}{\partial r} v_r + \frac{v_r}{r} \\ &\quad + \frac{1}{r} (\sin^2 \theta + \cos^2 \theta) v_r + 0 \\ &\quad + \frac{1}{r} (\sin^2 \theta + \cos^2 \theta) \frac{\partial v_\theta}{\partial \theta} \\ &\quad + \frac{\partial v_z}{\partial z} \end{aligned}$$

$$\operatorname{div} \vec{v} = \frac{\partial v_r}{\partial r} + \frac{v_r}{r} + \frac{1}{r} \frac{\partial}{\partial \theta} v_\theta + \frac{\partial}{\partial z} v_z$$

### Exercice 3.



On applique le théorème de la divergence :

$$\int_{\Omega} \operatorname{div} \vec{E}(\vec{x}) \, d\Omega = \int_{\partial\Omega} \vec{E}(\vec{x}) \cdot \vec{n} \, dS$$

$$\int_{\Omega} e(\vec{x}) \, d\Omega = 2 \int_{-1/2}^{1/2} \int_{-1/2}^{1/2} E_x(x) \, dy \, dz = 2E_x(x)$$

$$\text{si } x < 1 \quad \int_{\Omega} e(\vec{x}) \, d\Omega = 2 \int_0^x \int_{-1/2}^{1/2} \int_{-1/2}^{1/2} (1-x) \, dz \, dy \, dx$$

$$= 2 \left( x - \frac{x^2}{2} \right) \Rightarrow E_x(x) = x - \frac{x^2}{2}$$

$$\text{si } x > 1 \quad \int_{\Omega} e(\vec{x}) \, d\Omega = 2 \int_0^1 \int_{-1/2}^{1/2} \int_{-1/2}^{1/2} (1-x) \, dz \, dy \, dx$$

$$= 1 \Rightarrow E_x(x) = \frac{1}{2}$$

### Exercice 4:

Théorème de la divergence :

$$\int_{B_r} \operatorname{div} \vec{E}(\vec{x}) \, d\mu = \int_{S_r} \vec{E} \cdot \vec{n} \, dS = 4\pi r^2 E_r(r)$$

si  $r < R$

$$\int_0^r \int_0^{2\pi} \int_0^{2\pi} \left(1 - \frac{r^2}{R^2}\right) r^2 \sin \theta \, d\varphi \, d\theta \, dr$$

$$= \int_0^r \left(1 - \frac{r^2}{R^2}\right) 4\pi r^2 \, dr = 4\pi \left( \frac{r^3}{3} - \frac{r^3}{5} \cdot \frac{r^2}{R^2} \right)$$
$$= \frac{4\pi}{15} r^3 \left( \frac{4}{3} - \frac{r^2}{5R^2} \right)$$

$$E_r(r) = \frac{4\pi}{15} r \left( \frac{4}{3} - \frac{r^2}{5R^2} \right)$$

si  $r > R$

$$\int_{B_r} \operatorname{div} \vec{E}(\vec{x}) \, d\mu = 4\pi R^3 \cdot \frac{2}{15}$$

$$E_r(r) = \frac{2}{15} \frac{R^3}{r^2}$$

### Exercice 5:

$$\int_0^r \int_0^{2\pi} \operatorname{rot} B \cdot \vec{n} \, r \, dr \, d\theta = \int \vec{B} \cdot d\vec{\ell}$$

$$\int_0^r \int_0^{2\pi} r^2 \, dr \, d\theta = 2\pi r B_\theta(r)$$

$$2\pi \frac{r^3}{3} = 2\pi r B_\theta(r)$$

$$B_\theta(r) = \frac{r^2}{3}$$

